Packing Plane Spanning Trees into a Point Set

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Abstract

Let P be a set of n points in the plane in general position. We show that at least $\lfloor n/3 \rfloor$ plane spanning trees can be packed into the complete geometric graph on P. This improves the previous best known lower bound $\Omega\left(\sqrt{n}\right)$. Towards our proof of this lower bound we show that the center of a set of points, in the d-dimensional space in general position, is of dimension either 0 or d.

1 Introduction

In the two-dimensional space, a geometric graph G is a graph whose vertices are points in the plane and whose edges are straight-line segments connecting the points. A subgraph S of G is plane if no pair of its edges cross each other. Two subgraphs S_1 and S_2 of G are edge-disjoint if they do not share any edge.

Let P be a set of n points in the plane. The complete geometric graph K(P) is the geometric graph with vertex set P that has a straight-line edge between every pair of points in P. We say that a sequence S_1, S_2, S_3, \ldots of subgraphs of K(P) is packed into K(P), if the subgraphs in this sequence are pairwise edge-disjoint. In a packing problem, we ask for the largest number of subgraphs of a given type that can be packed into K(P). Among all subgraphs, plane spanning trees, plane Hamiltonian paths, and plane perfect matchings are of interest. Since K(P) has n(n-1)/2 edges, at most $\lfloor n/2 \rfloor$ spanning trees, at most $\lfloor n/2 \rfloor$ Hamiltonian paths, and at most n-1 perfect matchings can be packed into it.

A long-standing open question is to determine whether or not it is possible to pack $\lfloor n/2 \rfloor$ plane spanning trees into K(P). If P is in convex position, the answer in the affirmative follows from the result of Bernhart and Kanien [3], and a characterization of such plane spanning trees is given by Bose et al. [5]. In CCCG 2014, Aichholzer et al. [1] showed that if P is in general position (no three points on a line), then $\Omega(\sqrt{n})$ plane spanning trees can be packed into K(P); this bound is obtained by a clever combination of crossing family (a set of pairwise crossing edges) [2] and double-stars (trees with only two interior nodes) [5]. Schnider [12] showed that it is not always possible to pack $\lfloor n/2 \rfloor$ plane spanning double stars into K(P), and gave a necessary and sufficient condition for the existence of such a packing. As for packing other spanning structures into K(P), Aichholzer et al. [1] and Biniaz et al. [4] showed a packing of 2 plane Hamiltonian cycles and a packing of $\lceil \log_2 n \rceil - 2$ plane perfect matchings, respectively.

The problem of packing spanning trees into (abstract) graphs is studied by Nash-Williams [11] and Tutte [13] who independently obtained necessary and sufficient conditions to pack k spanning trees into a graph. Kundu [10] showed that at least $\lceil (k-1)/2 \rceil$ spanning trees can be packed into any k-edge-connected graph.

In this paper we show how to pack $\lfloor n/3 \rfloor$ plane spanning trees into K(P) when P is in general position. This improves the previous $\Omega(\sqrt{n})$ lower bound.

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2 Packing Plane Spanning Trees

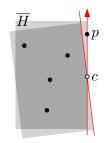
In this section we show how to pack $\lfloor n/3 \rfloor$ plane spanning tree into K(P), where P is a set of $n \ge 3$ points in the plane in general position (no three points on a line). If $n \in \{3, 4, 5\}$ then one can easily find a plane spanning tree on P. Thus, we may assume that $n \ge 6$.

The center of P is a subset C of the plane such that any closed halfplane intersecting C contains at least $\lceil n/3 \rceil$ points of P. A centerpoint of P is a member of C, which does not necessarily belong to P. Thus, any halfplane that contains a centerpoint, has at least $\lceil n/3 \rceil$ points of P. It is well known that every point set in the plane has a centerpoint; see e.g. $\lceil 7 \rceil$, Chapter 4. We use the following corollary and lemma in our proof of the $\lceil n/3 \rceil$ lower bound; the corollary follows from Theorem 3 that we will prove later in Section 3.

Corollary 1. Let P be a set of $n \ge 6$ points in the plane in general position, and let C be the center of P. Then, C is either 2-dimensional or 0-dimensional. If C is 0-dimensional, then it consists of one point that belongs to P, moreover n is of the form 3k+1 for some integer $k \ge 2$.

Lemma 1. Let P be a set of n points in the plane in general position, and let c be a centerpoint of P. Then, for every point $p \in P$, each of the two closed halfplanes, that are determined by the line through c and p, contains at least $\lceil n/3 \rceil + 1$ points of P.

Proof. For the sake of contradiction assume that a closed halfplane \overline{H} , that is determined by the line through c and p, contains less than $\lceil n/3 \rceil + 1$ points of P. By symmetry assume that \overline{H} is to the left side of this line oriented from c to p; see the figure to the right. Since c is a centerpoint and \overline{H} contains c, the definition of centerpoint implies that \overline{H} contains exactly $\lceil n/3 \rceil$ points of P (including p and any other point of P that may lie on the boundary of \overline{H}). By slightly rotating \overline{H} counterclockwise around c, while keeping c on the boundary of \overline{H} , we obtain a new closed halfplane that contains c but



misses p. This new halfplane contains less than $\lceil n/3 \rceil$ points of P; this contradicts c being a centerpoint of P.

Now we proceed with our proof of the lower bound. We distinguish between two cases depending on whether the center C of P is 2-dimensional or 0-dimensional. First suppose that C is 2-dimensional. Then, C contains a centerpoint, say c, that does not belong to P. Let p_1, \ldots, p_n be a counter-clockwise radial ordering of points in P around c. For two points p and q in the plane, we denote by \overrightarrow{pq} , the ray emanating from p that passes through q.

Since every integer $n \ge 3$ has one of the forms 3k, 3k+1, and 3k+2, for some $k \ge 1$, we will consider three cases. In each case, we show how to construct k plane spanning directed graphs G_1, \ldots, G_k that are edge-disjoint. Then, for every $i \in \{1, \ldots, k\}$, we obtain a plane spanning tree T_i from G_i . First assume that n=3k. To build G_i , connect p_i by outgoing edges to $p_{i+1}, p_{i+2}, \ldots, p_{i+k}$, then connect p_{i+k} by outgoing edges to $p_{i+k+1}, p_{i+k+2}, \ldots, p_{i+2k}$, and then connect p_{i+2k} by outgoing edges to $p_{i+2k+1}, p_{i+2k+2}, \ldots, p_{i+3k}$, where all the indices are modulo n, and thus $p_{i+3k} = p_i$. The graph G_i , that is obtained this way, has one cycle $(p_i, p_{i+k}, p_{i+2k}, p_i)$; see Figure 1. By Lemma 1, every closed halfplane, that is determined by the line through c and a point of c, contains at least c 1 points of c 2. Thus, all points c 3 points c 4 points c 4 points c 5 points c 6 points c 7 points c 8 points c 8 points c 9 points c

Therefore, the spanning directed graph G_i is plane. As depicted in Figure 1, by removing the edge (p_{i+2k}, p_i) from G_i we obtain a plane spanning (directed) tree T_i . This is the end of our construction of k plane spanning trees.

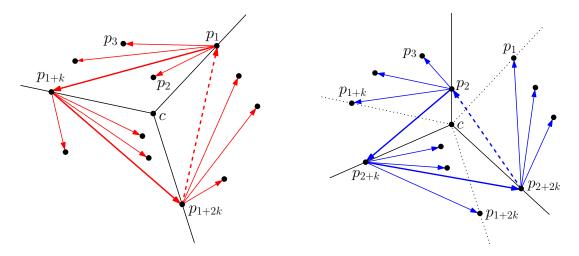


Figure 1: The plane spanning trees T_1 (the left) and T_2 (the right) are obtained by removing the edges (p_{1+2k}, p_1) and (p_{2+2k}, p_2) from G_1 and G_2 , respectively.

To verify that the k spanning trees obtained above are edge-disjoint, we show that two trees T_i and T_j , with $i \neq j$, do not share any edge. Notice that the tail of every edge in T_i belongs to the set $I = \{p_i, p_{i+k}, p_{i+2k}\}$, and the tail of every edge in T_j belongs to the set $J = \{p_j, p_{j+k}, p_{j+2k}\}$, and $I \cap J = \emptyset$. For contrary, suppose that some edge (p_r, p_s) belongs to both T_i and T_j , and without loss of generality assume that in T_i this edge is oriented from p_r to p_s while in T_j it is oriented from p_s to p_r . Then $p_r \in I$ and $p_s \in J$. Since $(p_r, p_s) \in T_i$ and the largest index of the head of every outgoing edge from p_r is r + k, we have that $s \leq (r + k)$ mod p_s . Similarly, since p_s is p_s to p_s and the largest index of the head of every outgoing edge from p_s is p_s is p_s to the head of every outgoing edge from p_s is p_s to the head of every outgoing edge from p_s is p_s to the head of every outgoing edge from p_s is p_s to the head of every outgoing edge from p_s is p_s to the head of every outgoing edge from p_s is p_s to the head of every outgoing edge from p_s is p_s to the head of every outgoing edge from p_s is p_s to the head of every outgoing edge from p_s is p_s to the head of every outgoing edge from p_s is p_s to the head of every outgoing edge from p_s is p_s to the head of every outgoing edge from p_s is p_s to the head of every outgoing edge from p_s is p_s to the head of every outgoing edge from p_s is p_s to the head of every outgoing edge from p_s is p_s to the head of every outgoing edge from p_s is p_s to the head of every outgoing edge from p_s is p_s to the head of every outgoing edge from p_s is p_s to the head of every outgoing edge from p_s to the head of every outgoing edge from p_s to the head of every outgoing edge from p_s to the head of every outgoing edge from p_s to the head of every outgoing edge from p_s to t

If n = 3k + 1, then by Lemma 1, every closed halfplane that is determined by the line through c and a point of P contains at least k + 2 points of P. In this case, we construct G_i by connecting p_i to its following k + 1 points, i.e., $p_{i+1}, \ldots, p_{i+k+1}$, and then connecting each of p_{i+k+1} and p_{i+2k+1} to their following k points. If n = 3k + 2, then we construct G_i by connecting each of p_i and p_{i+k+1} to their following k + 1 points, and then connecting p_{i+2k+2} to its following k points. This is the end of our proof for the case where C is 2-dimensional.

Now we consider the case where C is 0-dimensional. By Corollary 1, C consists of one point that belongs to P, and moreover n=3k+1 for some $k \geq 2$. Let $p \in P$ be the only point of C, and let p_1, \ldots, p_{n-1} be a counter-clockwise radial ordering of points in $P \setminus \{p\}$ around p. As in our first case (where C was 2-dimensional, c was not in P, and n was of the form 3k) we construct k edge-disjoint plane spanning trees T_1, \ldots, T_k on $P \setminus \{p\}$ where p playing the role of c. Then, for every $i \in \{1, \ldots, k\}$, by connecting p to p_i , we obtain a plane spanning tree for P. These plane spanning trees are edge-disjoint. This is the end of our proof. In this section we have proved the following theorem.

Theorem 1. Every complete geometric graph, on a set of n points in the plane in general position, contains at least $\lfloor n/3 \rfloor$ edge-disjoint plane spanning trees.

3 The Dimension of the Center of a Point Set

The *center* of a set P of $n \ge d+1$ points in \mathbb{R}^d is a subset C of \mathbb{R}^d such that any closed halfspace intersecting C contains at least $\alpha = \lceil n/(d+1) \rceil$ points of P. Based on this definition, one can characterize C as the intersection of all closed halfspaces such that their complementary open halfspaces contain less than α points of P. More precisely (see [7, Chapter 4]) C is the intersection of a finite set of closed halfspaces $\overline{H_1}, \overline{H_2}, \ldots, \overline{H_m}$ such that for each $\overline{H_i}$

- 1. the boundary of $\overline{H_i}$ contains at least d affinely independent points of P, and
- 2. the complementary open halfspace H_i contains at most $\alpha 1$ points of P, and the closure of H_i contains at least α points of P.

Being the intersection of closed halfspaces, C is a convex polyhedron. A centerpoint of P is a member of C, which does not necessarily belong to P. It follows, from the definition of the center, that any halfspace containing a centerpoint has at least α points of P. It is well known that every point set in the plane has a centerpoint [7, Chapter 4]. In dimensions 2 and 3, a centerpoint can be computed in O(n) time [9] and in $O(n^2)$ expected time [6], respectively.

A set of points in \mathbb{R}^d , with $d \geq 2$, is said to be in *general position* if no k+2 of them lie in a k-dimensional flat for every $k \in \{1, \ldots, d-1\}$. Alternatively, for a set of points in \mathbb{R}^d to be in general position, it suffices that no d+1 of them lie on the same hyperplane. In this section we prove that if a point set P in \mathbb{R}^d is in general position, then the center of P is of dimension either 0 or d. Our proof of this claim uses the following result of Grünbaum.

Theorem 2 (Grünbaum, 1962 [8]). Let \mathcal{F} be a finite family of convex polyhedra in \mathbb{R}^d , let I be their intersection, and let s be an integer in $\{1,\ldots,d\}$. If every intersection of s members of \mathcal{F} is of dimension d, but I is (d-s)-dimensional, then there exist s+1 members of \mathcal{F} such that their intersection is (d-s)-dimensional.

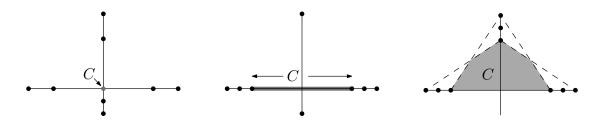


Figure 2: The dimension of a point set in the plane, that is not in general position, can be any number in $\{0, 1, 2\}$.

Before proceeding to our proof, we note that if P is not in general position, then the dimension of C can be any number in $\{0, 1, \ldots, d\}$; see e.g. Figure 2 for the case where d = 2.

Observation 1. For every $k \in \{1, ..., d+1\}$ the dimension of a polyhedron defined by intersection of k closed halfspaces in \mathbb{R}^d is in the range [d-k+1,d].

Theorem 3. Let P be a set of $n \ge d+1$ points in \mathbb{R}^d , and let C be the center of P. Then, C is either d-dimensional, or contained in a (d-s)-dimensional polyhedron that has at least $n-(s+1)(\alpha-1)$ points of P for some $s \in \{1,\ldots,d\}$ and $\alpha = \lceil n/(d+1) \rceil$. In the latter case if P is in general position and $n \ge d+3$, then C consists of one point that belongs to P, and n is of the form k(d+1)+1 for some integer $k \ge 2$.

 $^{^{1}}$ A flat is a subset of d-dimensional space that is congruent to a Euclidean space of lower dimension. The flats in 2-dimensional space are points and lines, which have dimensions 0 and 1.

Proof. The center C is a convex polyhedron that is the intersection of a finite family \mathcal{H} of closed halfspaces such that each of their complementary open halfspaces contains at most $\alpha - 1$ points of P [7, Chapter 4]. Since C is a convex polyhedron in \mathbb{R}^d , its dimension is in the range [0, d]. For the rest of the proof we consider the following two cases.

- (a) The intersection of every d+1 members of \mathcal{H} is of dimension d.
- (b) The intersection of some d+1 members of \mathcal{H} is of dimension less than d.

First assume that we are in case (a). We prove that C is d-dimensional. Our proof follows from Theorem 2 and a contrary argument. Assume that C is not d-dimensional. Then, C is (d-s)-dimensional for some $s \in \{1, \ldots, d\}$. Since the intersection of every s members of \mathcal{H} is d-dimensional, by Theorem 2 there exist s+1 members of \mathcal{H} whose intersection is (d-s)-dimensional. This contradicts the assumption of case (a) that the intersection of every d+1 members of \mathcal{H} is d-dimensional. Therefore, C is d-dimensional in this case.

Now assume that we are in case (b). Let s be the largest integer in $\{1,\ldots,d\}$ such that every intersection of s members of \mathcal{H} is d-dimensional; notice that such an integer exists because every single halfspace in \mathcal{H} is d-dimensional. Our choice of s implies the existence of a subfamily \mathcal{H}' of s+1 members of \mathcal{H} whose intersection is d'-dimensional for some d' < d. Let s' be an integer such that d' = d - s'. By Observation 1, we have that $d' \geqslant d - s$, and equivalently $d - s' \geqslant d - s$; this implies $s' \leqslant s$. To this end we have a family \mathcal{H}' with s+1 members for which every intersection of s' members is d-dimensional (because $s' \leqslant s$ and $\mathcal{H}' \subseteq \mathcal{H}$), but the intersection of all members of \mathcal{H}' is (d - s')-dimensional. Applying Theorem 2 on \mathcal{H}' implies the existence of s'+1 members of \mathcal{H}' whose intersection is (d-s')-dimensional. If s' < s, then this implies the existence of $s'+1 \leqslant s$ members of $\mathcal{H}' \subseteq \mathcal{H}$, whose intersection is of dimension d-s' < d. This contradicts the fact that the intersection of every s members of \mathcal{H} is d-dimensional. Thus, s'=s, and consequently, d'=d-s'=d-s. Therefore C is contained in a (d-s)-dimensional polyhedron I which is the intersection of the s+1 closed halfspaces of \mathcal{H}' . Let H_1,\ldots,H_{s+1} be the complementary open halfspaces of members of \mathcal{H}' , and recall that each H_i contains at most $\alpha-1$ points of P. Let \overline{I} be the complement of I. Then,

$$n = |I \cup \overline{I}| = |I \cup H_1 \cup \dots \cup H_{s+1}|$$

$$\leq |I| + |H_1| + \dots + |H_{s+1}| \leq |I| + (s+1)(\alpha - 1),$$

where we abuse the notations I, \overline{I} , and H_i to refer to the subset of points of P that they contain. This inequality implies that I contains at least $n - (s+1)(\alpha - 1)$ points of P. This finishes the proof of the theorem except for the part that P is in general position.

Now, assume that P is in general position and $n \ge d+3$. By the definition of general position, the number of points of P in a (d-s)-dimensional flat is not more than d-s+1. Since I is (d-s)-dimensional, this implies that

$$n - (s+1)(\alpha - 1) \leqslant d - s + 1.$$

Notice that n is of the form k(d+1)+i for some integer $k \ge 1$ and some $i \in \{0,1,\ldots,d\}$. Moreover, if i is 0 or 1, then $k \ge 2$ because $n \ge d+3$. Now we consider two cases depending on whether or not i is 0. If i=0, then $\alpha=k$. In this case, the above inequality simplifies to $k(d-s) \le d-2s$, which is not possible because $k \ge 2$ and $d \ge s \ge 1$. If $i \in \{1,\ldots,d\}$, then $\alpha=k+1$. In this case, the above inequality simplifies to $(k-1)(d-s)+i \le 1$, which is not possible unless d=s and i=1. Thus, for the above inequality to hold we should have d=s and i=1. These two assertions imply that n=k(d+1)+1, and that i=1 is 0-dimensional and consists of one point of i=1. Since i=1 and i=1 is not empty, i=1 and i=1 and i=1 is 0-dimensional and consists of one point of i=1.

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