Plane Sweep

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• Input: Given a set S of n line segments

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- Output: All pairs $s, t \in S$ such that s intersects t

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- **1**. for each $s, t \in \binom{S}{2}$
 - ▶ if *s* intersects *t* then add (*s*, *t*) to the output

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- Then the size of the output is $\binom{n}{2} = \Omega(n^2)$

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- The Bently-Ottman plane-sweep algorithm runs in time O((n+k) log n) where k is the number of intersecting pairs of segments

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• This is much faster when
$$k \ll \binom{n}{2}$$

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- During intersection events, we record the intersecting pairs
- Simplifying assumptions:
 - No segment is vertical
 - No three segments intersect in the same point



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Image: A = 1



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- The sweep-line status is a SortedSet that stores the segments that currently intersect the sweep line, ordered from top to bottom (y-coordinate)
- The event queue is a PriorityQueue that stores events (segment endpoints and intersections) ordered from left to rigth (x-coordinate)



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• set the x-coordinate of the sweep line to $-\infty$

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- \blacktriangleright set the x-coordinate of the sweep line to $-\infty$
- add all 2n segment endpoints to the event queue

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- For the right endpoints of a segment *s*:
 - Remove s from the sweep line status
 - Check if the element above and below s cross and add a crossing event to the event queue if necessary

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- ▶ To process a crossing event where *s* and *t* cross:
 - Switch the order of s and t in the sweep line status
 - Check if s or t intersects the new elements above and below them in the sweep line and add crossing events to the event queue if necessary



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The Plane Sweep Algorithm is correct because any pair s, t that crosses will eventually become adjacent in the sweep-line status structure.

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- The Plane Sweep Algorithm is correct because any pair s, t that crosses will eventually become adjacent in the sweep-line status structure.
 - When they become adjacent, their crossing event is added to the event queue

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• We process 2n + k events

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 - Adding an element to the event queue: $O(\log n)$
 - ▶ Getting an element from the event queue: $O(\log n)$
 - Seaching the sweepline status: O(log n)
- ► Total running time is therefore (2n+k) · O(log n) = O((n+k) log n)

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► A data structure for the planar point location problem: O(n log n) space and O(log n) query time